



Stern- und  
Planetenentstehung  
Sommersemester 2020  
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Lecture 3: Gas Flows and Turbulence



[http://exp-astro.physik.uni-frankfurt.de/star\\_formation/index.php](http://exp-astro.physik.uni-frankfurt.de/star_formation/index.php)

## VORLESUNG/LECTURE

Raum: Physik - 02.201a

dienstags, 12:00 - 14:00 Uhr

## SPRECHSTUNDE:

Raum: GSC, 1/34, Tel.: 47433, (roellig@ph1.uni-koeln.de)

dienstags: 14:00-16:00 Uhr

| Nr. | Thema   | Termin     |
|-----|---|------------|
| 1   | Observing the cold ISM  | 21.04.2020 |
| 2   | Observing Young Stars   | 28.04.2020 |
| 3   | Gas Flows and Turbulence<br>Magnetic Fields and Magnetized Turbulence | 05.05.2020 |
| 4   | Gravitational Instability and Collapse                                | 12.05.2020 |
| 5   | Stellar Feedback  | 19.05.2020 |
| 6   | Giant Molecular Clouds  | 26.05.2020 |
| 7   | Star Formation Rate at Galactic Scales                                | 02.06.2020 |
| 8   | Stellar Clustering  | 09.06.2020 |
| 9   | Initial Mass Function – Observations and Theory                       | 16.06.2020 |
| 10  | Massive Star Formation  | 23.06.2020 |
| 11  | Protostellar disks and outflows – observations and theory             | 30.06.2020 |
| 12  | Protostar Formation and Evolution                                     | 07.07.2020 |
| 13  | Late Stage stars and disks – planet formation                         | 14.07.2020 |

# 3 GAS FLOWS AND TURBULENCE

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## 3.1 CHARACTERISTIC NUMBERS FOR FLUID FLOW

### 3.1.1 The Conservation Equations

Fluids are governed by a series of conservation laws

conservation of mass:

$$\frac{\partial}{\partial t} \rho = -\nabla \cdot (\rho \vec{v})$$

change of mass density at a fixed point is equal to minus the divergence of density times velocity = rate at which mass flows into or out of an infinitesimal volume around that point

conservation of momentum:

$$\frac{\partial}{\partial t} (\rho \vec{v}) = -\nabla \cdot (\rho \vec{v} \vec{v}) - \nabla P + \rho \nu \nabla^2 \vec{v}$$

( $\vec{v} \vec{v}$ : tensor product, (outer product) -> index notation)

$$\frac{\partial}{\partial t} (\rho v_i) = -\frac{\partial}{\partial x_j} \cdot (\rho v_i v_j) - \frac{\partial}{\partial x_i} P + \rho \nu \frac{\partial}{\partial x_j} \left( \frac{\partial}{\partial x_j} v_i \right)$$

viscosity  $\nu$

$\rho \vec{v}$ : density of momentum at a point

$\nabla \cdot (\rho \vec{v} \vec{v})$ : analog to cons. of mass rate at which momentum is advected into or out of the point by the flow

$\nabla P$ : rate at which pressure forces acting on the fluid changes its momentum

$\rho \nu \nabla^2 \vec{v}$ : rate at which viscosity redistributes momentum (This is the only term without analogous counterpart in Newton's second law for single particles)

$\nu$ : kinematic viscosity

The viscous term describes the change in fluid momentum due to diffusion of momentum from adjacent fluid elements.

fluid velocity = systematic flow + random velocity field ↗

viscosity turns bulk motion into random motion => dissipation

### 3.1.2 The Reynolds Number and the Mach Number

To understand rel. importance of terms in momentum equation

⇒ dimensional analysis

system of characteristic size  $L$  and characteristic velocity  $V$

(mol. cloud:  $L \sim 10 \text{ pc}$ ,  $V \sim 5 \text{ km s}^{-1}$ )

the natural time scale for such a system:  $L/V$

$$\Rightarrow \left( \frac{\partial X}{\partial t} \sim \frac{X}{\frac{L}{V}} \right) \quad \text{and} \quad \left( \frac{\partial X}{\partial x} \sim \frac{X}{L} \right)$$

momentum equation ( $P = \rho c_s^2$ ,  $c_s$  = gas sound speed):

$$\frac{\rho V^2}{L} \sim \frac{\rho V^2}{L} + \frac{\rho c_s^2}{L V^2} + \rho \frac{V}{V L^2}$$

$/: \frac{V^2}{L}$

$$1 \sim 1 + \frac{c_s^2}{V^2} + \frac{v}{V L}$$

$\uparrow \frac{1}{M^2} \quad \uparrow \frac{1}{Re} \sim \nu$

We define:

$$\text{Mach number} \quad \mathcal{M} \sim \frac{V}{c_s}$$

$$\text{Reynolds number} \quad Re \sim \frac{LV}{\nu}$$

If  $\mathcal{M} \ll 1$  then  $\frac{c_s^2}{V^2} \gg 1$  pressure term is important

$\mathcal{M} \gg 1$  pressure term unimportant

$$c_s = \sqrt{\frac{k_B T}{\mu m_H}} = 0.18 \left( \frac{T}{10K} \right)^{1/2}, \quad \mu = 2.33 \text{ (mean mass per particle)}$$

assuming 1He per 10 H  $\Rightarrow 14/6$ )

$$\Rightarrow \frac{MV}{c_s} \sim 20 \quad \Rightarrow \text{pressure forces unimportant in mol. clouds}$$

If  $Re \lesssim 1$  viscous forces are important

$Re \gg 1$  viscous forces are unimportant

Reynolds number describes characteristic length scale  $L \sim \nu/V$  in the flow

This is the length scale on which diffusion causes the flow to dissipate energy  $\Rightarrow$  large scale motion effectively dissipationless.

ideal gas:  $\nu = 2\bar{u}\lambda$   $\bar{u}$ : RMS molecular speed (order of  $c_s$ )

$\lambda$ : particle mean free path

(inverse of cross-section times density)

$$\lambda \sim \frac{1}{\sigma n} \sim [1(nm)^2 (100cm^{-3})]^{-1} \sim 10^{12} \text{ cm}$$

$$\nu \sim 10^{16} \text{ cm}^2 \text{ s}^{-1} \text{ and } Re \sim 10^9$$

$\Rightarrow$  viscous forces are unimportant in molecular clouds



⇒ molecular clouds must be highly turbulent! (turbulent if  $Re \gtrsim 10^3 - 10^4$ )

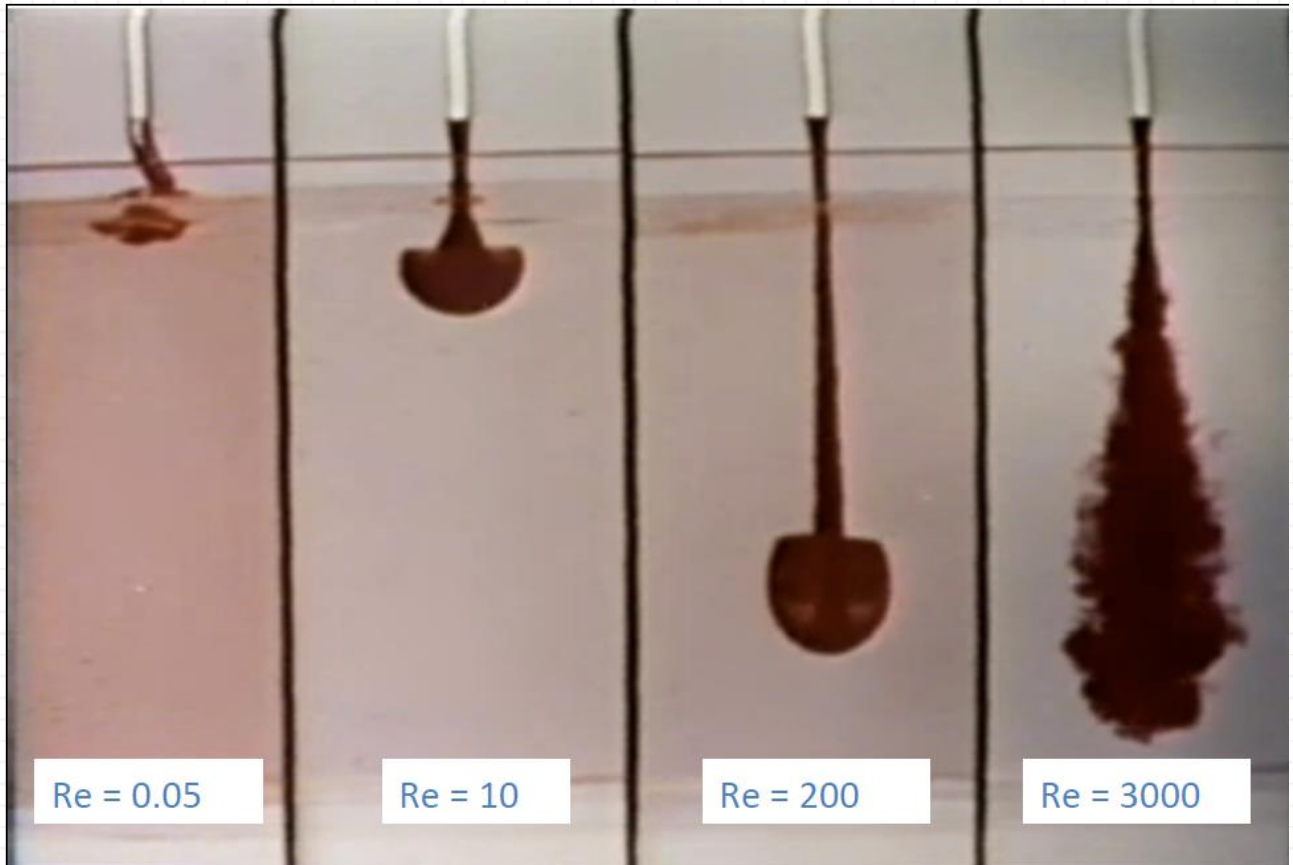


Abbildung 1 National Committee for Fluid Mechanics Films (NCFMF) / Taylor 1964)

(see video)

## 3.2 MODELLING TURBULENCE

### 3.2.1 Velocity Statistics

Important property of turbulence: velocity structure, i.e. how does the velocity change from point to point

In turbulent medium, velocity fluctuates in time and space => statistical study

Assumptions:

- homogeneous turbulence (turbulent motions vary only randomly, not systematically)
- isotropic turbulence (no preferred direction)  
(neither are true for mol. clouds!)

Autocorrelation function characterizes how  $\vec{v}$  varies with position



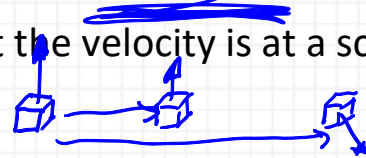
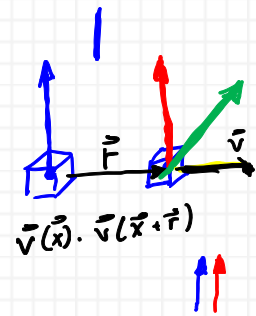
$$A(\vec{r}) = \frac{1}{V} \int \vec{v}(\vec{x}) \cdot \vec{v}(\vec{x} + \vec{r}) dV \equiv \langle \vec{v}(\vec{x}) \cdot \vec{v}(\vec{x} + \vec{r}) \rangle$$

$\langle \dots \rangle$  indicate average over all positions

$A(0) = \langle |\vec{v}|^2 \rangle$  RMS velocity in the fluid

Isotropicity:  $A(\vec{r})$  cannot depend on direction  $\rightarrow \vec{r} \rightarrow |\vec{r}|$

$A(r)$  measures how different the velocity is at a scale  $r$



Alternatively, in Fourier space: the Fourier transform of the velocity field:

$$\tilde{v}(\vec{k}) = \frac{1}{\sqrt{2\pi}} \int \vec{v}(\vec{x}) e^{i\vec{k} \cdot \vec{x}} d\vec{x}$$

The the power spectrum is:

$$\Psi(\vec{k}) = |\tilde{v}(\vec{k})|^2$$

Again, because of isotropicity, the power spectrum depends only on the magnitude of the wave number  $k = |\vec{k}|$ , not its direction.

Instead of  $\Psi$  we use the power per unit radius in  $k$ -space:

$$P(\vec{k}) = 4\pi k^2 \Psi(k)$$

(Total power integrated over some shell from  $k$  to  $dk$  in  $k$ -space.)

Parseval's Theorem

$$\int P(k) dk = \int |\tilde{v}(\vec{k})|^2 d^3\vec{k} = \int \vec{v}(\vec{x})^2 d^3\vec{x}$$

$E_{kin} \propto v^2$

Integral over power spectral density over all wavenumbers is equal to the integral of the square of the velocity over all space

$\Rightarrow$  if  $\rho = const$  the integral of the power spectrum is the kinetic energy per unit mass in the flow!

## Wiener-Khinchin Theorem

$P(k)$  is just the Fourier transform of the autocorrelation function

$$\Psi(\vec{k}) = \frac{1}{(2\pi)^{3/2}} \int A(\vec{r}) e^{i\vec{k}\cdot\vec{r}} d\vec{r}$$

- ⇒ Power spectrum at wavenumber  $k \rightarrow$  fraction of total power is in motions at that wavenumber, i.e. on that characteristic length scale ( $k = 2\pi/\lambda$ ).
- ⇒ A power spectrum that peaks at low  $k \rightarrow$  most of the turbulent power is in large-scale motions
- ⇒ A power spectrum that peaks at high  $k \rightarrow$  most of the turbulent power is in small-scale motions
- ⇒ The power spectrum also specifies how the velocity dispersions varies when measured over a region of some characteristic size.

Consider a volume of size  $l$  and a velocity dispersion  $\sigma_v(l)$  within it.

Suppose that the power spectrum is described by a power law

$P(k) \propto k^{-n}$ . The total kinetic energy per unit within the region is

$$KE \sim \sigma_v(l)^2$$

Above, we saw that we can also write the kinetic energy in terms of the power spectrum integrating over those modes that are small enough to fit within the volume

$$KE \sim \int_{2\pi/l}^{\infty} P(k) dk \propto l^{n-1}$$

normalizing, by defining the sonic scale  $l_s$  as the size of a region within which the velocity dispersion is equal to the thermal sound speed of gas, it follows that:

$$\sigma_v = c_s \left( \frac{l}{l_s} \right)^{\frac{n-1}{2}}$$



### 3.2.2 The Kolmogorov Model and Turbulence Cascades

Basic theory of subsonic, hydrodynamic turbulence: Kolmogorov (1941)  
(translation: Kolmogorov (1991))

- turbulence occurs when  $Re$  is large (large range of scales where dissipation is unimportant)
- for incompressible motion transfer of energy can only occur between adjacent wavenumbers
  - energy at a scale  $k$  cannot be transferred directly to some scale  $k' \ll k$
  - instead it must cascade through intermediate scales between  $k$  and  $k'$

Energy is injected into a system on some large scale that is dissipationless and it cascades down to smaller scales until at some scale  $Re \sim 1$  at which dissipation becomes important.

If turbulence is in equilibrium, the energy at some scale  $k$  depends only on  $k$  and on the rate of injection (or dissipation, which are equal)  $\psi$ .

Dimensional analysis:

$k \sim 1/L$ , power spectrum  $\sim$  energy per unit mass ( $\sim v^2 = L^2/T^2$ ) per unit radius in  $k$ -space ( $\sim 1/L$ )  $P(k) \sim L^3/T^2$ ,  $\psi \sim L^2/T^3$

$P(k)$  is a function of  $k$  and  $\psi$  we write (for some dimensionless  $C$ )

$$P(k) = C k^\alpha \psi^\beta$$

Then

$$\frac{L^3}{T^2} \sim L^{-\alpha} \left( \frac{L^2}{T^3} \right)^\beta$$

$$L^3 \sim L^{-\alpha+2\beta}$$

$$T^{-2} \sim T^{-3\beta}$$

$$\beta = \frac{2}{3}$$

$$\alpha = 2\beta - 3 = -\frac{5}{3}$$

- power in the flow varies with energy injection rate to the  $\frac{2}{3}$
- power distributed such that the power at a given wavenumber  $k$  varies as  $k^{-5/3}$ 
  - most power in the largest scale motion
- we find that  $\sigma_v \propto l^{1/3}$ 
  - velocity dispersion increases with size scale as size to the  $\frac{1}{3}$
  - linewidth-size relation
    - larger regions should have larger linewidths

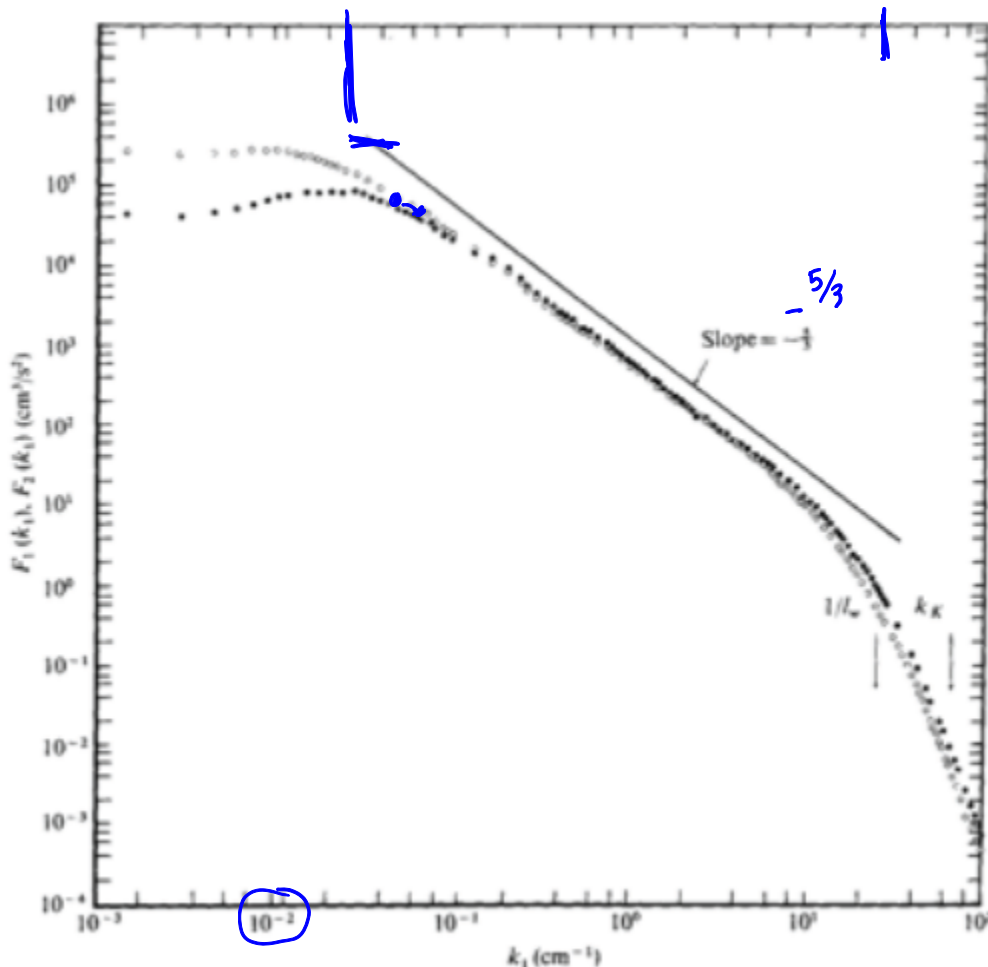
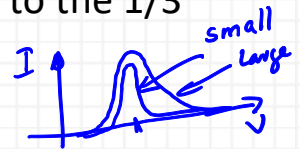


Abbildung 2 Power spectrum for turbulence generated in an air jet (Champagne 1978)

## 3.3 SUPERSONIC TURBULENCE

### 3.3.1 Velocity Statistics

real interstellar clouds:  $Re \gg 1$ ,  $\mathcal{M} \gg 1$  supersonic  
pressure unimportant on scales  $L \gg l_s$   
viscosity also unimportant on large scales

- gas tends to move ballistically on large scales
- on small scales sharp velocity gradients (fast volumes will overtake slow volumes)
- eventually viscosity will stop the fluid from moving ballistically
  - ⇒ shocks (size scale determined by viscosity)

velocity field: series of step functions

power spectrum:  $P(k) \propto k^{-2}$

subsonic turbulence:  $k^{-5/3}$   $-5/3$  energy decay via cascade to small scales

supersonic turbulence  $-2$  decay via shock formation

(one single shock generates  $P(k) \propto k^{-2}$ . i.e. nonlocally couples many scales)

- ⇒ all scales are coupled in shocks

### 3.3.2 Density Statistics

in subsonic flows, the dominant pressure leads to ~constant density in isothermal gas

in supersonic flows -> highly compressible -> structure of density field

From numerical experiments and empirical arguments:

supersonically turbulent, isothermal medium -> log-normal distribution

$$p(s) = \frac{1}{\sqrt{2\pi\sigma_s^2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma_s^2}\right], \quad \text{where } s = \ln\left(\frac{\rho}{\bar{\rho}}\right)$$

$s$ : log of density normalized to mean density  $\bar{\rho}$ ,  $s_0$ : median of distribution

probability that the density at a randomly chosen point will be such that  $\ln(\rho/\bar{\rho})$  is in the range from  $s$  to  $s + ds$ .

Because  $\bar{\rho} = \int p(s)\rho ds = e^{s_0 + \sigma_s^2/2}$  we find:  $s_0 = -\sigma_s^2/2$

probability that a randomly chosen mass element will have a particular density:

consider a volume  $V$ , all material with density such that  $\ln(\rho/\bar{\rho})$  is in the range from  $s$  to  $s + ds$ . This material occupies a volume  $dV = p(s)V$  and has a mass:

$$\begin{aligned} dM &= \rho p(s) dV \\ &= \bar{\rho} e^s \frac{1}{\sqrt{2\pi\sigma_s^2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma_s^2}\right] dV \end{aligned}$$

$$p_M(s) = \frac{1}{\sqrt{2\pi\sigma_s^2}} \exp\left[-\frac{(s+s_0)^2}{2\sigma_s^2}\right] dV$$

The mass PDF is the same as the volume PDF but with the peak shifted from  $-s_0$  to  $+s_0$ :

- ⇒ typical volume element is at a density lower than the mean (because mass is collected into shocks)
- ⇒ typical mass element is in those shocked regions and is at a higher than average density

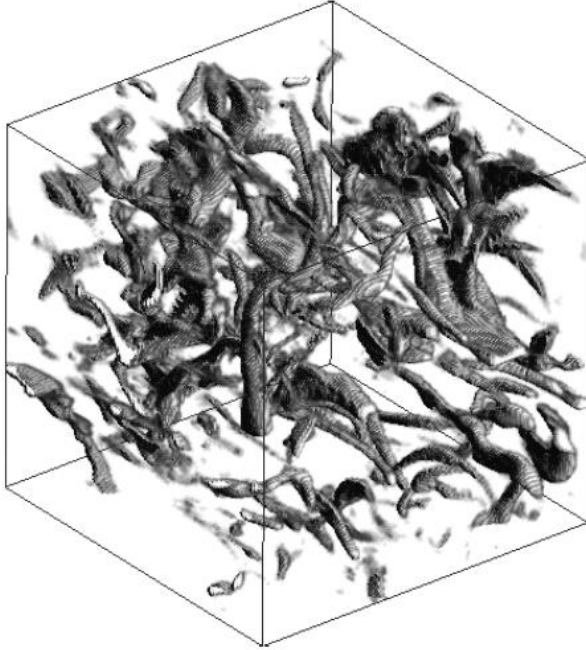


Abbildung 3 Density field of supersonic turbulence (Padoan Z& Nordlund 1999)

Supersonic turbulence:

series of shocks and rarefaction

density multiplied by factors > and < 1

A log-normal process is the statistical realization of the multiplicative product of many independent random variables, each of which is positive.

log-normal in density

dispersion of densities (empirically from num. simulations)

$$\sigma_s^2 \approx \ln \left( 1 + b^2 \mathcal{M}^2 \frac{\beta_0}{\beta_0 + 1} \right)$$

$b$  is a number in the 1/3-1 (depends on how compressive vs. selenoidal) the velocity field is

$\beta_0$  is the ratio of thermal to magnetic pressure at the mean density and magnetic field strength

## 4 MAGNETIC FIELDS AND MAGNETIZED TURBULENCE

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